Package 'scip'

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Title Interface to the SCIP Optimization Suite

Version 1.10.0-3

Description
Provides an R interface to SCIP (Solving Constraint Integer Programs), a framework for mixed-integer
programming (MIP), mixed-
integer nonlinear programming (MINLP), and constraint integer programming
(2025, <doi:10.48550/arXiv.2511.18580>). Supports linear, quadratic, SOS, indicator, and knapsack
constraints with continuous, binary, and integer variables. Includes a one-shot solver interface
and a model-building API for incremental problem construction.

License Apache License (>= 2)

URL https://bnaras.github.io/scip/, https://scipopt.org/

BugReports https://github.com/bnaras/scip/issues

Depends R (>= 4.0)

Imports methods, Matrix

Suggests tinytest, slam, knitr, rmarkdown

VignetteBuilder knitr

SystemRequirements CMake (>= 3.11), GNU make, C++17

Encoding UTF-8

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NeedsCompilation yes

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Contents

`print.scip_control` *Print method for scip_control objects*

Description

Print method for scip_control objects

Usage

```
## S3 method for class 'scip_control'
print(x, ...)
```

Arguments

`x`	A `scip_control` object.
`...`	Ignored.

Value

Invisible `x`.

scip_add_indicator_cons

Add an indicator constraint to a SCIP model

Description

If `binvar = 1` then `sum(coefs * x[vars]) <= rhs`.

Usage

```
scip_add_indicator_cons(model, binvar, vars, coefs, rhs, name = NULL)
```

Arguments

`model`	A SCIP model.
`binvar`	Integer; 1-based index of the binary indicator variable.
`vars`	Integer vector; 1-based variable indices.
`coefs`	Numeric vector; coefficients.
`rhs`	Numeric; right-hand side.
`name`	Character; constraint name.

Value

Integer; 1-based constraint index.

scip_add_linear_cons *Add a linear constraint to a SCIP model*

Description

Adds `lhs <= sum(coefs * x[vars]) <= rhs`.

Usage

```
scip_add_linear_cons(model, vars, coefs, lhs = -Inf, rhs = Inf, name = NULL)
```

Arguments

`model`	A SCIP model.
`vars`	Integer vector; 1-based variable indices.
`coefs`	Numeric vector; coefficients (same length as `vars`).
`lhs`	Numeric; left-hand side. Default `-Inf`.
`rhs`	Numeric; right-hand side. Default `Inf`.
`name`	Character; constraint name. Default auto-generated.

Value

Integer; 1-based constraint index.

`scip_add_quadratic_cons` *Add a quadratic constraint to a SCIP model*

Description

Adds `lhs <= linexpr + quadexpr <= rhs` where `quadexpr = sum(quadcoefs[k] * x[quadvars1[k]] * x[quadvars2[k]])`.

Usage

```
scip_add_quadratic_cons(
  model,
  linvars = integer(0),
  lincoefs = double(0),
  quadvars1 = integer(0),
  quadvars2 = integer(0),
  quadcoefs = double(0),
  lhs = -Inf,
  rhs = Inf,
  name = NULL
)
```

Arguments

`model`	A SCIP model.
`linvars`	Integer vector; 1-based variable indices for linear part.
`lincoefs`	Numeric vector; linear coefficients.
`quadvars1`, `quadvars2`	Integer vectors; 1-based variable indices for quadratic terms.
`quadcoefs`	Numeric vector; quadratic coefficients.
`lhs`, `rhs`	Numeric; constraint bounds.
`name`	Character; constraint name.

Value

Integer; 1-based constraint index.

scip_add_sos1_cons *Add a SOS1 constraint to a SCIP model*

Description

At most one variable in the set can be nonzero.

Usage

```
scip_add_sos1_cons(model, vars, weights = NULL, name = NULL)
```

Arguments

model	A SCIP model.
vars	Integer vector; 1-based variable indices.
weights	Numeric vector; weights determining branching order.
name	Character; constraint name.

Value

Integer; 1-based constraint index.

scip_add_sos2_cons *Add a SOS2 constraint to a SCIP model*

Description

At most two adjacent variables in the set can be nonzero.

Usage

```
scip_add_sos2_cons(model, vars, weights = NULL, name = NULL)
```

Arguments

model	A SCIP model.
vars	Integer vector; 1-based variable indices.
weights	Numeric vector; weights determining adjacency order.
name	Character; constraint name.

Value

Integer; 1-based constraint index.

scip_add_var *Add a variable to a SCIP model*

Description

Add a variable to a SCIP model

Usage

```
scip_add_var(model, obj, lb = 0, ub = Inf, vtype = "C", name = NULL)
```

Arguments

model	A SCIP model (external pointer from scip_model).
obj	Numeric; objective coefficient.
lb	Numeric; lower bound. Default 0.
ub	Numeric; upper bound. Default Inf.
vtype	Character; variable type: "C" (continuous), "B" (binary), or "I" (integer). Default "C".
name	Character; variable name. Default auto-generated.

Value

Integer; 1-based variable index.

scip_add_vars *Add multiple variables to a SCIP model*

Description

Add multiple variables to a SCIP model

Usage

```
scip_add_vars(model, obj, lb = 0, ub = Inf, vtype = "C", names = NULL)
```

Arguments

model	A SCIP model.
obj	Numeric vector; objective coefficients.
lb	Numeric; lower bounds (scalar or vector). Default 0.
ub	Numeric; upper bounds (scalar or vector). Default Inf.
vtype	Character; variable types (scalar or vector). Default "C".
names	Character vector; variable names. Default auto-generated.

Value

Integer; 1-based index of first variable added.

`scip_control` *SCIP solver control parameters*

Description

Create a list of control parameters for the SCIP solver. Parameters are organized into logical groups: output, limits, tolerances, presolving, LP, branching, and heuristics. Any SCIP parameter can also be set directly using its native path via ....

Usage

```
scip_control(
  verbose = TRUE,
  verbosity_level = 3L,
  display_freq = 100L,
  time_limit = Inf,
  node_limit = -1L,
  stall_node_limit = -1L,
  sol_limit = -1L,
  best_sol_limit = -1L,
  mem_limit = Inf,
  restart_limit = -1L,
  gap_limit = 0,
  abs_gap_limit = 0,
  feastol = 1e-06,
  dualfeastol = 1e-07,
  epsilon = 1e-09,
  presolving = TRUE,
  presolve_rounds = -1L,
  lp_threads = 1L,
  lp_iteration_limit = -1L,
  lp_scaling = TRUE,
  branching_score = "p",
  heuristics_emphasis = "default",
  threads = 1L,
  ...
)
```

Arguments

`verbose`	Logical; print solver output. Default `TRUE`.
`verbosity_level`	Integer 0–5; verbosity detail. Default `3`.

`display_freq` Integer; node display frequency. Default `100`.

`time_limit` Numeric; time limit in seconds. Default `Inf`.

`node_limit` Integer; max nodes. Default `-1L`.

`stall_node_limit` Integer; stall nodes. Default `-1L`.

`sol_limit` Integer; solution limit. Default `-1L`.

`best_sol_limit` Integer; improving solution limit. Default `-1L`.

`mem_limit` Numeric; memory limit in MB. Default `Inf`.

`restart_limit` Integer; restart limit. Default `-1L`.

`gap_limit` Numeric; relative MIP gap. Default `0`.

`abs_gap_limit` Numeric; absolute gap. Default `0`.

`feastol` Numeric; feasibility tolerance. Default `1e-6`.

`dualfeastol` Numeric; dual feasibility tolerance. Default `1e-7`.

`epsilon` Numeric; zero tolerance. Default `1e-9`.

`presolving` Logical; enable presolving. Default `TRUE`.

`presolve_rounds` Integer; presolve rounds. Default `-1L`.

`lp_threads` Integer; LP solver threads. Default `1L`.

`lp_iteration_limit` Integer; LP iteration limit. Default `-1L`.

`lp_scaling` Logical; LP scaling. Default `TRUE`.

`branching_score` Character; score function. Default `"p"`.

`heuristics_emphasis` Character; heuristic emphasis. Default `"default"`.

`threads` Integer; parallel solving threads. Default `1L`. See Parallel section for caveats.

`...` Additional SCIP parameters as name-value pairs, using SCIP's native hierarchical parameter paths (e.g., `"lp/fastmip" = 1`, `"conflict/enable" = FALSE`). See the SCIP parameter documentation for the full list.

Value

A named list of class `"scip_control"` with components:

`verbose` Logical; verbosity flag.

`scip_params` Named list; all parameters as SCIP native paths.

Output

`verbose` Logical; print solver output. Default `TRUE`.

`verbosity_level` Integer 0–5; verbosity detail (0 = none, 3 = normal, 5 = full). Default `3`. Ignored if `verbose = FALSE`.

`display_freq` Integer; display a status line every this many nodes (`-1` = never). Default `100`.

Termination Limits

`time_limit` Numeric; maximum solving time in seconds. Default `Inf` (no limit).

`node_limit` Integer; maximum number of branch-and-bound nodes. Default `-1L` (no limit).

`stall_node_limit` Integer; nodes without improvement before stopping. Default `-1L` (no limit).

`sol_limit` Integer; stop after finding this many feasible solutions. Default `-1L` (no limit).

`best_sol_limit` Integer; stop after this many improving solutions. Default `-1L` (no limit).

`mem_limit` Numeric; memory limit in MB. Default `Inf` (no limit).

`restart_limit` Integer; maximum restarts. Default `-1L` (no limit).

Tolerances

`gap_limit` Numeric; relative MIP gap tolerance; solver stops when the gap falls below this value. Default `0` (prove optimality).

`abs_gap_limit` Numeric; absolute gap between primal and dual bound. Default `0`.

`feastol` Numeric; feasibility tolerance for LP constraints. Default `1e-6`.

`dualfeastol` Numeric; dual feasibility tolerance. Default `1e-7`.

`epsilon` Numeric; absolute values below this are treated as zero. Default `1e-9`.

Presolving

`presolving` Logical; enable presolving. Default `TRUE`.

`presolve_rounds` Integer; maximum presolving rounds (`-1` = unlimited). Default `-1L`.

LP

`lp_threads` Integer; number of threads for LP solver. Default `1L`.

`lp_iteration_limit` Integer; LP iteration limit per solve (`-1` = no limit). Default `-1L`.

`lp_scaling` Logical; enable LP scaling. Default `TRUE`.

Branching

`branching_score` Character; branching score function: `"s"` (sum), `"p"` (product), `"q"` (quotient). Default `"p"`.

Heuristics

`heuristics_emphasis` Character; heuristic emphasis setting: `"default"`, `"aggressive"`, `"fast"`, or `"off"`. Default `"default"`.

Parallel

`threads` Integer; number of threads for concurrent solving. Default `1L`. Note: concurrent solving may require a SCIP build compiled with parallel support (e.g., `PARASCIP=true`); not all installations provide this.

See Also

scip_solve, scip_set_param

Examples

```
## Quick solve with 60-second time limit
ctrl <- scip_control(time_limit = 60)

## Quiet solve with 1% gap tolerance
ctrl <- scip_control(verbose = FALSE, gap_limit = 0.01)

## Aggressive heuristics, no presolving
ctrl <- scip_control(heuristics_emphasis = "aggressive", presolving = FALSE)

## Pass a native SCIP parameter directly
ctrl <- scip_control("conflict/enable" = FALSE, "separating/maxrounds" = 5L)
```

---

scip_get_info *Get solver information*

Description

Get solver information

Usage

```
scip_get_info(model)
```

Arguments

model	A SCIP model (after scip_optimize).

Value

A list with solve_time, nodes, iterations, gap, sol_count.

---

scip_get_nsols *Get number of solutions found*

Description

Get number of solutions found

Usage

```
scip_get_nsols(model)
```

Arguments

model	A SCIP model (after scip_optimize).

Value

Integer.

---

scip_get_objval *Get objective value of best solution*

Description

Get objective value of best solution

Usage

```
scip_get_objval(model)
```

Arguments

model	A SCIP model (after scip_optimize).

Value

Numeric; objective value, or NA if no solution.

---

scip_get_sol *Get the k-th solution from the solution pool*

Description

Get the k-th solution from the solution pool

Usage

```
scip_get_sol(model, k)
```

Arguments

model	A SCIP model.
k	Integer; 1-based solution index (1 = best).

Value

A list with objval and x.

scip_get_solution *Get the best solution*

Description

Get the best solution

Usage

```
scip_get_solution(model)
```

Arguments

model	A SCIP model (after scip_optimize).

Value

A list with objval and x.

scip_get_status *Get solver status*

Description

Get solver status

Usage

```
scip_get_status(model)
```

Arguments

model	A SCIP model (after scip_optimize).

Value

Character; status string (e.g., "optimal", "infeasible").

scip_model *Create a SCIP model*

Description

Creates a new SCIP optimization model for incremental problem construction.

Usage

```
scip_model(name = "scip_model")
```

Arguments

name	Character; problem name. Default "scip_model".

Value

An external pointer representing the SCIP model.

scip_model_free *Free a SCIP model*

Description

Explicitly frees the SCIP model and all associated memory. The model is also freed automatically when garbage collected.

Usage

```
scip_model_free(model)
```

Arguments

model	A SCIP model.

Value

Invisible NULL.

scip_optimize *Solve a SCIP model*

Description

Solve a SCIP model

Usage

```
scip_optimize(model)
```

Arguments

model	A SCIP model.

Value

Invisible NULL. Use scip_get_status and scip_get_solution to retrieve results.

scip_set_objective_sense *Set objective sense*

Description

Set objective sense

Usage

```
scip_set_objective_sense(model, sense = "minimize")
```

Arguments

model	A SCIP model.
sense	Character; "minimize" (default) or "maximize".

Value

Invisible NULL.

scip_set_param *Set a SCIP parameter*

Description

Set a SCIP parameter

Usage

```
scip_set_param(model, name, value)
```

Arguments

model	A SCIP model.
name	Character; SCIP parameter name (e.g., "limits/time").
value	The parameter value (type is auto-detected by SCIP).

Value

Invisible NULL.

scip_solve *Solve a linear or mixed-integer program using SCIP*

Description

One-shot interface to the SCIP solver. Formulates and solves:

$$\min_x \ obj'x$$

subject to constraint rows defined by A, b, sense, with variable types vtype and bounds lb, ub.

Usage

```
scip_solve(obj, A, b, sense, vtype = "C", lb = 0, ub = Inf, control = list())
```

Arguments

obj	Numeric vector of length n; objective coefficients.
A	Constraint matrix (m x n). Can be a dense matrix, dgCMatrix, or simple_triplet_matrix.
b	Numeric vector of length m; constraint right-hand side.
sense	Character vector of length m; constraint sense. Each element must be "<=", ">=", or "==".

vtype	Character; variable types. Either a single value applied to all variables, or a vector of length n. Values: "C" (continuous), "B" (binary), "I" (integer). Default "C".
lb	Numeric; lower bounds for variables. Single value or vector of length n. Default 0.
ub	Numeric; upper bounds for variables. Single value or vector of length n. Default Inf.
control	A list of solver parameters, typically from scip_control.

Value

A named list with components:

status Character; solver status (e.g., "optimal", "infeasible", "unbounded").

objval Numeric; optimal objective value (or NA if no solution).

x Numeric vector; primal solution (or NULL if no solution).

sol_count Integer; number of solutions found.

gap Numeric; relative optimality gap.

info List with additional solver information (solve_time, iterations, nodes).

Index